

Package ‘ENMeval’

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Type Package

Title Automated Tuning and Evaluations of Ecological Niche Models

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Description Runs ecological niche models over all combinations of user-defined settings (i.e., tuning), performs cross validation to evaluate models, and returns data tables to aid in selection of optimal model settings that balance goodness-of-fit and model complexity. Also has functions to partition data spatially (or not) for cross validation, to plot multiple visualizations of results, to run null models to estimate significance and effect sizes of performance metrics, and to calculate niche overlap between model predictions, among others. The package was originally built for Maxent models (Phillips et al. 2006, Phillips et al. 2017), but the current version allows possible extensions for any modeling algorithm. The extensive vignette, which guides users through most package functionality but unfortunately has a file size too big for CRAN, can be found here on the package's Github Pages website: <<https://jamiemkass.github.io/ENMeval/articles/ENMeval-2.0.0-vignette.html>>.

License GPL

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| | |
|-----------------|------------------------------------------------------------------|
| ENMeval-package | <i>Automated runs and evaluations of ecological niche models</i> |
|-----------------|------------------------------------------------------------------|

Description

Runs ecological niche models over all combinations of user-defined settings (i.e., tuning), performs cross validation to evaluate models, and returns data tables to aid in selection of optimal model settings that balance goodness-of-fit and model complexity. Also has functions to partition data spatially (or not) for cross validation, to plot multiple visualizations of results, to run null models to estimate significance and effect sizes of performance metrics, and to calculate niche overlap between model predictions, among others. The package was originally built for Maxent models (Phillips et al. 2006, Phillips et al. 2017), but the current version allows possible extensions for any

modeling algorithm. The extensive vignette, which guides users through most package functionality but unfortunately has a file size too big for CRAN, can be found here on the package's Github Pages website: <<https://jamiemkass.github.io/ENMeval/articles/ENMeval-2.0.0-vignette.html>>.

Details

See README for details.

Author(s)

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- Robert P. Anderson

aic.maxent

Calculate AICc from Maxent model prediction

Description

This function calculates AICc for Maxent models based on Warren and Seifert (2011).

Usage

```
aic.maxent(p.occs, ncoefs, p = NULL)
```

Arguments

| | |
|--------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| p.occs | data frame: raw (maxent.jar) or exponential (maxnet) predictions for the occurrence localities based on one or more models |
| ncoefs | numeric: number of non-zero model coefficients |
| p | RasterStack: raw (maxent.jar) or exponential (maxnet) model predictions; if NULL, AICc will be calculated based on the background points, which already have predictions that sum to 1 and thus need no correction – this assumes that the background points represent a good sample of the study extent |

Details

As motivated by Warren and Seifert (2011) and implemented in ENMTools (Warren *et al.* 2010), this function calculates the small sample size version of Akaike Information Criterion for ENMs (Akaike 1974). We use AICc (instead of AIC) regardless of sample size based on the recommendation of Burnham and Anderson (1998, 2004). The number of coefficients is determined by counting the number of non-zero coefficients in the maxent lambda file (m@lambdas for maxent.jar and m\$betas for maxnet. See Warren *et al.* (2014) for limitations of this approach, namely that the number of non-zero coefficients is an estimate of the true degrees of freedom. For Maxent ENMs, AICc is calculated by first standardizing the raw predictions such that all cells in the study extent sum to 1, then extracting the occurrence record predictions. The predictions of the study extent may not sum to 1 if the background does not cover every grid cell – as the background predictions sum to 1 by definition, extra predictions for grid cells not in the training data will add to this sum. When no raster data is provided, the raw predictions of the occurrence records are used to calculate AICc without standardization, with the assumption that the background records have adequately represented the occurrence records. The standardization is not necessary here because the background predictions sum to 1 already, and the occurrence data is a subset of the background. This will not be true if the background does not adequately represent the occurrence records, in which case the occurrences are not a subset of the background and the raster approach should be used instead. The likelihood of the data for a given model is then calculated by taking the product of the raw occurrence predictions (Warren and Seifert 2011), or the sum of their logs, as is implemented here.

Value

data frame with three columns: AICc is the Akaike Information Criterion corrected for small sample sizes calculated as:

$$(2 * K - 2 * \logLikelihood) + (2 * K) * (K + 1) / (n - K - 1)$$

where K is the number of non-zero coefficients in the model and n is the number of occurrence localities. The \logLikelihood is calculated as:

$$\text{sum}(\log(\text{vals}))$$

where vals is a vector of Maxent raw/exponential values at occurrence localities and the sum of these values across the study extent is equal to 1. delta.AICc is the difference between the AICc of a given model and the AICc of the model with the lowest AICc. w.AICc is the Akaike weight (calculated as the relative likelihood of a model ($\exp(-0.5 * \text{delta.AICc})$) divided by the sum of the likelihood values of all models included in a run. These can be used for model averaging (Burnham and Anderson 2002).

Note

Returns all NAs if the number of non-zero coefficients is larger than the number of observations (occurrence localities).

References

Akaike, H. (1974) A new look at the statistical model identification. *IEEE Transactions on Automatic Control*, **19**: 716-723. doi: [10.1109/TAC.1974.1100705](https://doi.org/10.1109/TAC.1974.1100705)

Burnham, K. P. and Anderson, D. R. (1998) Model selection and multimodel inference: a practical information-theoretic approach. Springer, New York.

Burnham, K. P. and Anderson, D. R. (2004) Multimodel inference: understanding AIC and BIC in model selection. *Sociological Methods and Research*, **33**: 261-304. doi: [10.1177/0049124104268644](https://doi.org/10.1177/0049124104268644)

Warren, D. L., Glor, R. E., and Turelli, M. (2010) ENMTools: a toolbox for comparative studies of environmental niche models. *Ecography*, **33**: 607-611. doi: [10.1111/j.16000587.2009.06142.x](https://doi.org/10.1111/j.16000587.2009.06142.x)

Warren, D. L., & Seifert, S. N. (2011). Ecological niche modeling in Maxent: the importance of model complexity and the performance of model selection criteria. *Ecological Applications*, **21**: 335-342. doi: [10.1890/101171.1](https://doi.org/10.1890/101171.1)

Warren, D. L., Wright, A. N., Seifert, S. N., and Shaffer, H. B. (2014). Incorporating model complexity and sampling bias into ecological niche models of climate change risks faced by 90 California vertebrate species of concern. *Diversity and Distributions*, **20**: 334-343. doi: [10.1111/ddi.12160](https://doi.org/10.1111/ddi.12160)

See Also

maxent in the **dismo** package.

boyce.cm

Continuous Boyce Index (modified from ecospat package)

Description

This function was modified from `ecospat::ecospat.boyce()` by Cory Merow to make it run faster. It retains the same functionality as the original function. Function parameter information is taken from `ecospat.boyce()`.

Usage

```
boyce.cm(fit, obs, nclass = 0, window.w = "default", res = 100, PEplot = TRUE)
```

Arguments

| | |
|-----------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <code>fit</code> | A vector or Raster-Layer containing the predicted suitability values |
| <code>obs</code> | A vector containing the predicted suitability values or xy-coordinates (if "fit" is a Raster-Layer) of the validation points (presence records) |
| <code>nclass</code> | The number of classes or vector with class thresholds. If <code>nclass=0</code> , the Boyce index is calculated with a moving window (see next parameters) |
| <code>window.w</code> | The width of the moving window (by default 1/10 of the suitability range) |
| <code>res</code> | The resolution of the moving window (by default 100 focals) |
| <code>PEplot</code> | If true, plot the predicted to expected ratio along the suitability class |

| | |
|----------|---------------------------------------------------|
| buildRMM | <i>Build metadata object from ENMeval results</i> |
|----------|---------------------------------------------------|

Description

Builds a rangeModelMetadata object from the output of ENMevaluate. See Merow *et al.* (2019) for more details on the nature of the metadata and the rangeModelMetadata package. To improve reproducibility of the study, this metadata object can be used as supplemental information for a manuscript, shared with collaborators, etc.

Usage

```
buildRMM(e, envs, rmm = NULL)
```

Arguments

| | |
|------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------|
| e | ENMevaluation object |
| envs | RasterStack: environmental predictor variables used in analysis; needed to pull information on the predictor variables not included in the ENMevaluation object |
| rmm | rangeModelMetadata object: if included, fields are appended to this RMM object as opposed to returning a new RMM object |

References

Merow, C., Maitner, B. S., Owens, H. L., Kass, J. M., Enquist, B. J., Jetz, W., & Guralnick, R. (2019). Species' range model metadata standards: RMMS. *Global Ecology and Biogeography*, **28**: 1912-1924. doi: [10.1111/geb.12993](https://doi.org/10.1111/geb.12993)

| | |
|-------------|------------------------------------|
| bvariegatus | <i>Example occurrence dataset.</i> |
|-------------|------------------------------------|

Description

An example occurrence dataset for the Brown Throated Sloth (*Bradypus variegatus*) downloaded from GBIF with the spocc package.

Usage

```
bvariegatus
```

Format

A data frame with 476 rows and 2 variables:

longitude The longitude coordinate (x).

latitude The latitude coordinate (y).

Source

<https://www.gbif.org/>

calc.10p.trainThresh *Calculate 10 percentile threshold*

Description

Function to calculate the 10 percentile threshold from training predictions

Usage

```
calc.10p.trainThresh(pred.train)
```

Arguments

pred.train numeric vector: training occurrence predictions

calc.niche.overlap *Calculate Similarity of ENMs in Geographic Space*

Description

Compute pairwise "niche overlap" in geographic space for Maxent predictions. The value ranges from 0 (no overlap) to 1 (identical predictions). The function uses the nicheOverlap function of the **dismo** package (Hijmans *et al.* 2011).

Usage

```
calc.niche.overlap(predictors, overlapStat, quiet = FALSE)
```

Arguments

predictors RasterStack: at least 2 Maxent raster predictions

overlapStat character: either "D" or "I", the statistic calculated by the nicheOverlap function of the **dismo** package (default: "D")

quiet boolean: if TRUE, silence all function messages (but not errors)

Details

"D" refers to Schoeners D (Schoener 1968), while "I" refers to the I similarity statistic from Warren *et al.* (2008).

Value

A matrix with the lower triangle giving values of pairwise "niche overlap" in geographic space. Row and column names correspond to the results table output by `ENMevaluate()`.

Author(s)

Based on `dismo::nicheOverlap`, which is based on `SDMTools::Istat` at Robert Muscarella <bob.muscarella@gmail.com>

References

Hijmans, R. J., Phillips, S., Leathwick, J. & Elith, J. (2011) `dismo` package for R. Available online at: <https://cran.r-project.org/package=dismo>.

Schoener, T. W. (1968) The *Anolis* lizards of Bimini: resource partitioning in a complex fauna. *Ecology*, **49**: 704-726. doi: [10.2307/1935534](https://doi.org/10.2307/1935534)

Warren, D. L., Glor, R. E., Turelli, M. & Funk, D. (2008) Environmental niche equivalency versus conservatism: quantitative approaches to niche evolution. *Evolution*, **62**: 2868-2883. doi: [10.1111/j.15585646.2008.00482.x](https://doi.org/10.1111/j.15585646.2008.00482.x)

See Also

'nicheOverlap' in the `dismo` package

clamp.vars

Clamp predictor variables

Description

This function restricts the values of one or more predictor variable rasters to stay within the bounds of the input occurrence and background data (argument "ref.vals"). This is termed "clamping", and is mainly used to avoid making extreme extrapolations when making model predictions to environmental conditions outside the range of the occurrence / background data used to train the model. Clamping can be done on variables of choice on one or both tails of their distributions (i.e., arguments "left" and "right" for minimum and maximum clamps, respectively). If "left" and/or "right" are not specified and left at the default NULL, the function will clamp all variables for that tail (thus, the function default is to clamp all variables on both sides). To turn off clamping for one side, enter "none" for either "left" or "right".

Categorical variables need to be declared with the argument "categoricals". These variables are excluded from the clamping analysis, but are put back into the RasterStack that is returned.

Usage

```
clamp.vars(orig.vals, ref.vals, left = NULL, right = NULL, categorical = NULL)
```

Arguments

| | |
|--------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| orig.vals | RasterStack / matrix / data frame: environmental predictor variables (must be in same geographic projection as occurrence data), or predictor variables values for the original records |
| ref.vals | matrix / data frame: predictor variable values for the reference records (not including coordinates), used to determine the minimums and maximums – this should ideally be the occurrences + background (can be made with raster::extract()) |
| left | character vector: names of variables to get a minimum clamp; can be "none" to turn off minimum clamping |
| right | character vector: names of variables to get a maximum clamp, can be "none" to turn off maximum clamping |
| categoricals | character vector: name or names of categorical environmental variables |

Value

The clamped Raster* object.

Author(s)

Stephen J. Phillips, Jamie M. Kass, Gonzalo Pinilla-Buitrago

| | |
|---------------|------------------------------------|
| corrected.var | <i>Corrected variance function</i> |
|---------------|------------------------------------|

Description

Calculate variance corrected for non-independence of k -fold iterations

Usage

```
corrected.var(x, nk)
```

Arguments

| | |
|----|-----------------------------------------|
| x | numeric vector: input values |
| nk | numeric: number of k -fold iterations |

Details

‘corrected.var’ calculates variance corrected for non-independence of k -fold iterations. See Appendix of Shcheglovitova & Anderson (2013) and other references (Miller 1974; Parr 1985; Shao and Wu 1989) for additional details. This function calculates variance that is corrected for the non-independence of k cross-validation iterations. Following Shao and Wu (1989):

$$SumOfSquares * ((n - 1)/n)$$

where n = the number of k -fold iterations.

Value

A numeric value of the corrected variance.

Author(s)

Robert Muscarella <bob.muscarella@gmail.com>

References

- Miller, R. G. (1974) The jackknife - a review. *Biometrika*, **61**: 1-15. doi: [10.1093/biomet/61.1.1](https://doi.org/10.1093/biomet/61.1.1)
- Parr, W. C. (1985) Jackknifing differentiable statistical functionals. *Journal of the Royal Statistics Society, Series B*, **47**: 56-66. doi: [10.1111/j.25176161.1985.tb01330.x](https://doi.org/10.1111/j.25176161.1985.tb01330.x)
- Shao J. and Wu, C. F. J. (1989) A general theory for jackknife variance estimation. *Annals of Statistics*, **17**: 1176-1197. doi: [10.1214/aos/1176347263](https://doi.org/10.1214/aos/1176347263)
- Shcheglovitova, M. and Anderson, R. P. (2013) Estimating optimal complexity for ecological niche models: a jackknife approach for species with small sample sizes. *Ecological Modelling*, **269**: 9-17. doi: [10.1016/j.ecolmodel.2013.08.011](https://doi.org/10.1016/j.ecolmodel.2013.08.011)

emp.bg

emp.bg generic for ENMnull object

Description

emp.bg generic for ENMnull object

Usage

```
emp.bg(x)
```

```
## S4 method for signature 'ENMnull'  
emp.bg(x)
```

Arguments

x ENMnull object

| | |
|------------|----------------------------------------------|
| emp.bg.grp | <i>emp.bg.grp generic for ENMnull object</i> |
|------------|----------------------------------------------|

Description

emp.bg.grp generic for ENMnull object

Usage

```
emp.bg.grp(x)

## S4 method for signature 'ENMnull'
emp.bg.grp(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

| | |
|----------|--------------------------------------------|
| emp.occs | <i>emp.occs generic for ENMnull object</i> |
|----------|--------------------------------------------|

Description

emp.occs generic for ENMnull object

Usage

```
emp.occs(x)

## S4 method for signature 'ENMnull'
emp.occs(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

| | |
|--------------|------------------------------------------------|
| emp.occs.grp | <i>emp.occs.grp generic for ENMnull object</i> |
|--------------|------------------------------------------------|

Description

emp.occs.grp generic for ENMnull object

Usage

```
emp.occs.grp(x)

## S4 method for signature 'ENMnull'
emp.occs.grp(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

| | |
|----------|-----------------------------------------------|
| enm.args | <i>enm.args generic for ENMdetails object</i> |
|----------|-----------------------------------------------|

Description

enm.args generic for ENMdetails object

Usage

```
enm.args(x)

enm.args(x) <- value

## S4 method for signature 'ENMdetails'
enm.args(x)

## S4 replacement method for signature 'ENMdetails'
enm.args(x) <- value
```

Arguments

| | |
|-------|-------------------|
| x | ENMdetails object |
| value | input value |

`enm.bioclim`*ENMdetails bioclim*

Description

This is the ENMdetails implementation for bioclim, implemented by dismo.

Usage

```
enm.bioclim
```

Format

An object of class ENMdetails of length 1.

`enm.errors`*enm.errors generic for ENMdetails object*

Description

`enm.errors` generic for ENMdetails object

Usage

```
enm.errors(x)
```

```
enm.errors(x) <- value
```

```
## S4 method for signature 'ENMdetails'  
enm.errors(x)
```

```
## S4 replacement method for signature 'ENMdetails'  
enm.errors(x) <- value
```

Arguments

`x` ENMdetails object

`value` input value

| | |
|---------|----------------------------------------------|
| enm.fun | <i>enm.fun generic for ENMdetails object</i> |
|---------|----------------------------------------------|

Description

enm.fun generic for ENMdetails object

Usage

```
enm.fun(x)
```

```
enm.fun(x) <- value
```

```
## S4 method for signature 'ENMdetails'  
enm.fun(x)
```

```
## S4 replacement method for signature 'ENMdetails'  
enm.fun(x) <- value
```

Arguments

| | |
|-------|-------------------|
| x | ENMdetails object |
| value | input value |

| | |
|----------------|------------------------------|
| enm.maxent.jar | <i>ENMdetails maxent.jar</i> |
|----------------|------------------------------|

Description

This is the ENMdetails implementation for maxent.jar, the Java version of the Maxent algorithm. The configuration for running the model differs slightly from that in previous versions of ENMeval (0.3.0 and before) in that this version (2.0.0) uses the default of adding presences to the background for model training, while previous versions had turned this off. Specifically, previous versions ran maxent() with "noaddsamplestobackground" in the "args" vector argument, while this version does not.

Usage

```
enm.maxent.jar
```

Format

An object of class ENMdetails of length 1.

| | |
|------------|--------------------------|
| enm.maxnet | <i>ENMdetails maxnet</i> |
|------------|--------------------------|

Description

This is the ENMdetails implementation for maxnet, the R version of the Maxent algorithm. The configuration for running the model now includes `addsamplestobackground = TRUE`, which explicitly adds presences to the background for model training, though as the current version of maxnet has this set to TRUE as default, behavior between ENMeval versions should not differ.

Usage

```
enm.maxnet
```

Format

An object of class ENMdetails of length 1.

| | |
|----------|-----------------------------------------------|
| enm.msgs | <i>enm.msgs generic for ENMdetails object</i> |
|----------|-----------------------------------------------|

Description

enm.msgs generic for ENMdetails object

Usage

```
enm.msgs(x)

enm.msgs(x) <- value

## S4 method for signature 'ENMdetails'
enm.msgs(x)

## S4 replacement method for signature 'ENMdetails'
enm.msgs(x) <- value
```

Arguments

| | |
|-------|-------------------|
| x | ENMdetails object |
| value | input value |

| | |
|----------|------------------------------------------------|
| enm.name | <i>eval.name generic for ENMdetails object</i> |
|----------|------------------------------------------------|

Description

eval.name generic for ENMdetails object

Usage

```
enm.name(x)
```

```
enm.name(x) <- value
```

```
## S4 method for signature 'ENMdetails'  
enm.name(x)
```

```
## S4 replacement method for signature 'ENMdetails'  
enm.name(x) <- value
```

Arguments

| | |
|-------|-------------------|
| x | ENMdetails object |
| value | input value |

| | |
|------------|-------------------------------------------------|
| enm.ncoefs | <i>enm.ncoefs generic for ENMdetails object</i> |
|------------|-------------------------------------------------|

Description

enm.ncoefs generic for ENMdetails object

Usage

```
enm.ncoefs(x)
```

```
enm.ncoefs(x) <- value
```

```
## S4 method for signature 'ENMdetails'  
enm.ncoefs(x)
```

```
## S4 replacement method for signature 'ENMdetails'  
enm.ncoefs(x) <- value
```

Arguments

| | |
|-------|-------------------|
| x | ENMdetails object |
| value | input value |

| | |
|-------------|--------------------------------------------------|
| enm.predict | <i>enm.predict generic for ENMdetails object</i> |
|-------------|--------------------------------------------------|

Description

enm.predict generic for ENMdetails object

Usage

```
enm.predict(x)

enm.predict(x) <- value

## S4 method for signature 'ENMdetails'
enm.predict(x)

## S4 replacement method for signature 'ENMdetails'
enm.predict(x) <- value
```

Arguments

| | |
|-------|-------------------|
| x | ENMdetails object |
| value | input value |

| | |
|------------|-------------------------------------------------|
| enm.varimp | <i>enm.varimp generic for ENMdetails object</i> |
|------------|-------------------------------------------------|

Description

enm.varimp generic for ENMdetails object

Usage

```
enm.varimp(x)

enm.varimp(x) <- value

## S4 method for signature 'ENMdetails'
enm.varimp(x)

## S4 replacement method for signature 'ENMdetails'
enm.varimp(x) <- value
```

Arguments

| | |
|-------|-------------------|
| x | ENMdetails object |
| value | input value |

| | |
|------------------|-------------------------|
| ENMdetails-class | <i>ENMdetails class</i> |
|------------------|-------------------------|

Description

An S4 class that details packages, functions, messages associated with a specific species distribution model (SDM) or ecological niche model (ENM). Objects of this class are generated by `ENMdetails()`. For examples, look in the package's R folder for scripts beginning with "enm" – these are pre-made ENMdetails object specifications that work with ENMeval out of the box.

Usage

```
## S4 method for signature 'ENMdetails'
show(object)
```

Arguments

object ENMdetails object

Slots

name character: name of algorithm

fun function: function that runs the algorithm

errors function: returns errors chosen by the user to prevent any malfunction in the analysis. The available arguments are: occs, envs, bg, tune.args, partitions, algorithm, partition.settings, other.settings, categoricals, doClamp, clamp.directions.

msgs function: prints messages showing the package version number, etc., and those related to the input tuning parameters tune.args. The available arguments are: tune.args, other.settings.

args function: returns the parameters needed to run the algorithm function. The available arguments are: occs.z, bg.z, tune.tbl.i, other.settings (where x.z is a data.frame of the envs values at coordinates of x, and tune.tbl.i is a single set of tuning parameters).

predict function: specifies how to calculate a model prediction for a Raster* or a data frame. The available arguments are: mod, envs, tune.tbl.i, other.settings.

ncoefs function: counts the number of non-zero model coefficients. The available arguments are: mod.

varimp function: generates a data frame of variable importance from the model object (if functionality is available). The available arguments are: mod.

Author(s)

Jamie M. Kass, <jamie.m.kass@gmail.com>

| | |
|-------------|---------------------------------------------------------------------------------------|
| ENMevaluate | <i>Tune ecological niche model (ENM) settings and calculate evaluation statistics</i> |
|-------------|---------------------------------------------------------------------------------------|

Description

ENMevaluate() is the primary function for the **ENMeval** package. This function builds ecological niche models iteratively across a range of user-specified tuning settings. Users can choose to evaluate models with cross validation or a full-withheld testing dataset. ENMevaluate() returns an ENMevaluation object with slots containing evaluation statistics for each combination of settings and for each cross validation fold therein, as well as raster predictions for each model when raster data is input. The evaluation statistics in the results table should aid users in identifying model settings that balance fit and predictive ability. See the extensive vignette for fully worked examples: <https://jamiemkass.github.io/ENMeval/articles/ENMeval-2.0.0-vignette.html>.

Usage

```
ENMevaluate(  
  occs,  
  envs = NULL,  
  bg = NULL,  
  tune.args = NULL,  
  partitions = NULL,  
  algorithm = NULL,  
  partition.settings = NULL,  
  other.settings = NULL,  
  categoricals = NULL,  
  doClamp = TRUE,  
  clamp.directions = NULL,  
  user.enm = NULL,  
  user.grp = NULL,  
  occs.testing = NULL,  
  taxon.name = NULL,  
  n.bg = 10000,  
  overlap = FALSE,  
  overlapStat = c("D", "I"),  
  user.val.grps = NULL,  
  user.eval = NULL,  
  rmm = NULL,  
  parallel = FALSE,  
  numCores = NULL,  
  parallelType = "doSNOW",  
  updateProgress = FALSE,  
  quiet = FALSE,  
  occ = NULL,  
  env = NULL,  
  bg.coords = NULL,
```

```

    RMvalues = NULL,
    fc = NULL,
    occ.grp = NULL,
    bg.grp = NULL,
    method = NULL,
    bin.output = NULL,
    rasterPreds = NULL,
    clamp = NULL,
    progbar = NULL
  )

```

Arguments

| | |
|---------------------------------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <code>occs</code> | matrix / data frame: occurrence records with two columns for longitude and latitude of occurrence localities, in that order. If specifying predictor variable values assigned to presence/background localities (without inputting raster data), this table should also have one column for each predictor variable. See Note for important distinctions between running the function with and without rasters. |
| <code>envs</code> | RasterStack: environmental predictor variables. These should be in same geographic projection as occurrence data. |
| <code>bg</code> | matrix / data frame: background records with two columns for longitude and latitude of background (or pseudo-absence) localities, in that order. If NULL, points will be randomly sampled across envs with the number specified by argument <code>n.bg</code> . If specifying predictor variable values assigned to presence/background localities (without inputting raster data), this table should also have one column for each predictor variable. See Details for important distinctions between running the function with and without rasters. |
| <code>tune.args</code> | named list: model settings to be tuned (i.e., for Maxent models: <code>list(fc = c("L", "Q"), rm = 1:3)</code>) |
| <code>partitions</code> | character: name of partitioning technique (see <code>?partitions</code>). |
| <code>algorithm</code> | character: name of the algorithm used to build models. Currently one of "maxnet", "maxent.jar", or "bioclim", else the name from a custom ENMdetails implementation. |
| <code>partition.settings</code> | named list: used to specify certain settings for partitioning schema. See Details and <code>?partitions</code> for descriptions of these settings. |
| <code>other.settings</code> | named list: used to specify extra settings for the analysis. All of these settings have internal defaults, so if they are not specified the analysis will be run with default settings. See Details for descriptions of these settings. |
| <code>categoricals</code> | character vector: name or names of categorical environmental variables. If not specified, all predictor variables will be treated as continuous unless they are factors. If categorical variables are already factors, specifying names of such variables in this argument is not needed. |
| <code>doClamp</code> | boolean: if TRUE (default), model prediction extrapolations will be restricted to the upper and lower bounds of the predictor variables. Clamping avoids extreme predictions for environment values outside the range of the training data. If extrapolation is a study aim, this should be set to FALSE. |

| | |
|------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <code>clamp.directions</code> | named list: specifies the direction ("left" for minimum, "right" for maximum) of clamping for predictor variables – (e.g., <code>list(left = c("bio1", "bio5"), right = c("bio10", "bio15"))</code>). |
| <code>user.enm</code> | ENMdetails object: a custom ENMdetails object used to build models. This is an alternative to specifying <code>algorithm</code> with a character string. |
| <code>user.grp</code> | named list: specifies user-defined partition groups, where <code>occs.grp</code> = vector of partition group (fold) for each occurrence locality, intended for user-defined partitions, and <code>bg.grp</code> = same vector for background (or pseudo-absence) localities. |
| <code>occs.testing</code> | matrix / data frame: a fully withheld testing dataset with two columns for longitude and latitude of occurrence localities, in that order when <code>partitions = "testing"</code> . These occurrences will be used only for evaluation but not for model training, and thus no cross validation will be performed. |
| <code>taxon.name</code> | character: name of the focal species or taxon. This is used primarily for annotating the ENMevaluation object and output metadata (<code>rmm</code>), but not necessary for analysis. |
| <code>n.bg</code> | numeric: the number of background (or pseudo-absence) points to randomly sample over the environmental raster data (default: 10000) if background records were not already provided. |
| <code>overlap</code> | boolean: if TRUE, calculate niche overlap statistics (Warren <i>et al.</i> 2008). |
| <code>overlapStat</code> | character: niche overlap statistics to be calculated – "D" (Schoener's D) and or "I" (Hellinger's I) – see <code>?calc.niche.overlap</code> for more details. |
| <code>user.val.grps</code> | matrix / data frame: user-defined validation record coordinates and predictor variable values. This is used internally by <code>ENMnulls()</code> to force each null model to evaluate with empirical validation data, and does not have any current use when running <code>ENMevaluate()</code> independently. |
| <code>user.eval</code> | function: custom function for specifying performance metrics not included in ENMeval . The function must first be defined and then input as the argument <code>user.eval</code> . This function should have a single argument called <code>vars</code> , which is a list that includes different data that can be used to calculate the metric. See Details below and the vignette for a worked example. |
| <code>rmm</code> | rangeModelMetadata object: if specified, <code>ENMevaluate()</code> will write metadata details for the analysis into this object, but if not, a new <code>rangeModelMetadata</code> object will be generated and included in the output ENMevaluation object. |
| <code>parallel</code> | boolean: if TRUE, run with parallel processing. |
| <code>numCores</code> | numeric: number of cores to use for parallel processing. If NULL, all available cores will be used. |
| <code>parallelType</code> | character: either "doParallel" or "doSNOW" (default: "doSNOW"). |
| <code>updateProgress</code> | boolean: if TRUE, use shiny progress bar. This is only for use in shiny apps. |
| <code>quiet</code> | boolean: if TRUE, silence all function messages (but not errors). |
| <code>occ, env, bg.coords, RMvalues, fc, occ.grp, bg.grp, method, bin.output, rasterPreds, clamp, progbar</code> | These arguments from previous versions are backward-compatible to avoid unnecessary errors for older scripts, but in a later version these arguments will be permanently deprecated. |

Details

There are a few methodological details in the implementation of ENMeval 2.0.0 that are important to mention. There is also a brief discussion of some points relevant to null models in ?ENMnulls.

1. By default, validation AUC is calculated with respect to the full background (training + validation). This approach follows Radosavljevic & Anderson (2014). This setting can be changed by assigning `other.settings$validation.bg` to "partition", which will calculate AUC with respect to the validation background only. The default value for `other.settings$validation.bg` is "full".

2. The continuous Boyce index (always) and AICc (when no raster is provided) are not calculated using the predicted values of the RasterStack delineating the full study extent, but instead using the predicted values for the background records. This decision to use the background only for calculating the continuous Boyce index was made to simplify the code and improve running time. The decision for AICc was made in order to allow AICc calculations for datasets that do not include raster data. See ?`calc.aicc` for more details, and for caveats when calculating AICc without raster data (mainly, that if the background does not adequately represent the occurrence records, users should use the raster approach, for reasons explained in the `calc.aicc` documentation). For both metrics, if the background records are a good representation of the study extent, there should not be much difference between this approach using the background data and the approach that uses rasters.

3. When running `ENMevaluate()` without raster data, and instead adding the environmental predictor values to the occurrence and background data tables, users may notice some differences in the results. Occurrence records that share a raster grid cell are automatically removed when raster data is provided, but without raster data this functionality cannot operate, and thus any such duplicate occurrence records can remain in the training data. The Java implementation of Maxent (`maxent.jar`) should automatically remove these records, but the R implementation `maxnet` does not, and the `bioclim()` function from the R package `dismo` does not as well. Therefore, it is up to the user to remove such records before running `ENMevaluate()` when raster data are not included.

Below are descriptions of the parameters used in the `other.settings`, `partition.settings`, and `user.eval` arguments.

For `other.settings`, the options are:

- * `abs.auc.diff` - boolean: if TRUE, take absolute value of AUCdiff (default: TRUE)
- * `pred.type` - character: specifies which prediction type should be used to generate `maxnet` or `maxent.jar` prediction rasters (default: "cloglog").
- * `validation.bg` - character: either "full" to calculate training and validation AUC and CBI for cross-validation with respect to the full background (default), or "partition" (meant for spatial partitions only) to calculate each with respect to the partitioned background only (i.e., training occurrences are compared to training background, and validation occurrences compared to validation background).
- * `other.args` - named list: any additional model arguments not specified for tuning.

For `partition.settings`, the current options are:

- * `orientation` - character: one of "lat_lon" (default), "lon_lat", "lat_lat", or "lon_lon" (required for block partition).
- * `aggregation.factor` - numeric vector: one or two numbers specifying the factor with which to aggregate the envs (default: 2) raster to assign partitions (required for the checkerboard partitions).
- * `kfolds` - numeric: the number of folds (i.e., partitions) for random partitions (default: 5).

For the block partition, the orientation specifications are abbreviations for "latitude" and "longitude", and they determine the order and orientations with which the block partitioning function creates the partition groups. For example, "lat_lon" will split the occurrence localities first by latitude, then by longitude. For the checkerboard partitions, the aggregation factor specifies how much to aggregate the existing cells in the envs raster to make new spatial partitions. For example, checkerboard1 with an aggregation factor value of 2 will make the grid cells 4 times larger and then assign occurrence and background records to partition groups based on which cell they are in. The checkerboard2 partition is hierarchical, so cells are first aggregated to define groups like checkerboard1, but a second aggregation is then made to separate the resulting 2 bins into 4 bins. For checkerboard2, two different numbers can be used to specify the two levels of the hierarchy, or if a single number is inserted, that value will be used for both levels.

For user.eval, the accessible variables you have access to in order to run your custom function are below. See the vignette for a worked example.

- * enm - ENMdetails object
- * occs.train.z - data frame: predictor variable values for training occurrences
- * occs.val.z - data frame: predictor variable values for validation occurrences
- * bg.train.z - data frame: predictor variable values for training background
- * bg.val.z - data frame: predictor variable values for validation background
- * mod.k - Model object for current partition (k)
- * nk - numeric: number of folds (i.e., partitions)
- * other.settings - named list: other settings specified in ENMevaluate()
- * partitions - character: name of the partition method (e.g., "block")
- * occs.train.pred - numeric: predictions made by mod.k for training occurrences
- * occs.val.pred - numeric: predictions made by mod.k for validation occurrences
- * bg.train.pred - numeric: predictions made by mod.k for training background
- * bg.val.pred - numeric: predictions made by mod.k for validation background

Value

An ENMevaluation object. See ?ENMevaluation for details.

References

Muscarella, R., Galante, P. J., Soley-Guardia, M., Boria, R. A., Kass, J. M., Uriarte, M., & Anderson, R. P. (2014). ENMeval: An R package for conducting spatially independent evaluations and estimating optimal model complexity for Maxent ecological niche models. *Methods in Ecology and Evolution*, **5**: 1198-1205. doi: [10.1111/2041210X.12261](https://doi.org/10.1111/2041210X.12261)

Warren, D. L., Glor, R. E., Turelli, M. & Funk, D. (2008) Environmental niche equivalency versus conservatism: quantitative approaches to niche evolution. *Evolution*, **62**: 2868-2883. doi: [10.1111/j.15585646.2008.00482.x](https://doi.org/10.1111/j.15585646.2008.00482.x)

Examples

```
## Not run:
occs <- read.csv(file.path(system.file(package="dismo"), "/ex/bradypus.csv"), [2:3]
envs <- raster::stack(list.files(path=paste(system.file(package="dismo"), "/ex", sep=""),
                                pattern="grd", full.names=TRUE))
occs.z <- cbind(occs, raster::extract(envs, occs))
occs.z$biome <- factor(occs.z$biome)
```



```

bg <- as.data.frame(dismo::randomPoints(envs, 1000))
names(bg) <- names(occs)
bg.z <- cbind(bg, raster::extract(envs, bg))
bg.z$biome <- factor(bg.z$biome)
tune.args <- list(fc = c("L", "LQ", "LQH", "H"), rm = 1:5)
os <- list(abs.auc.diff = FALSE, pred.type = "logistic", validation.bg = "partition")
ps <- list(orientation = "lat_lat")

e <- ENMevaluate(occs, envs, bg, tune.args = tune.args, partitions = "block",
other.settings = os, partition.settings = ps,
algorithm = "maxnet", categoricals = "biome", overlap = TRUE)

## End(Not run)

```

ENMevaluation-class *ENMevaluation class*

Description

An S4 class that contains the ENMevaluate results.

Usage

```

## S4 method for signature 'ENMevaluation'
show(object)

```

Arguments

object ENMevaluation object

Slots

algorithm character: algorithm used
tune.settings data frame: settings that were tuned
partition.method character: partition method used
partition.settings list: partition settings used (i.e., value of *k* or aggregation factor)
other.settings list: other modeling settings used (i.e., decisions about clamping, AUC diff calculation)
doClamp boolean: whether or not clamping was used
clamp.directions list: the clamping directions specified
results data frame: evaluation summary statistics
results.partitions data frame: evaluation k-fold statistics
models list: model objects
variable.importance list: variable importance data frames (when available)

predictions RasterStack: model predictions
 taxon.name character: the name of the focal taxon (optional)
 occs data frame: occurrence coordinates and predictor variable values used for model training
 occs.testing data frame: when provided, the coordinates of the fully-withheld testing records
 occs.grp vector: partition groups for occurrence points
 bg data frame: background coordinates and predictor variable values used for model training
 bg.grp vector: partition groups for background points
 overlap list: matrices of pairwise niche overlap statistics
 rmm list: the rangeModelMetadata objects for each model

Author(s)

Jamie M. Kass, <jamie.m.kass@gmail.com>, Bob Muscarella, <bob.muscarella@gmail.com>

ENMevaluation_convert *Convert old ENMevaluation objects to new ones*

Description

Converts ENMevaluation objects made with version $\leq 0.3.1$ to new ones made with version $\geq 2.0.0$.

Usage

```
ENMevaluation_convert(e, envs)
```

Arguments

| | |
|------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| e | ENMevaluation object: the old object to convert |
| envs | RasterStack: the original predictor variables used to generate the old ENMevaluation object (these are used to make the new occs and bg slots which contain the predictor variable values) |

Note

If bin.output was set to TRUE, `e@results` will be equivalent to the new results.partitions slot. Some slots are unable to be filled in because previous versions of ENMeval did not record them in ENMevaluation objects: variable.importance, partition.settings, other.settings, doClamp (set to TRUE arbitrarily to avoid errors, but may actually have been FALSE), clamp.directions, taxon.name, and rmm.

| | |
|-----------------|--------------------------------------|
| enmeval_results | <i>Example ENMevaluation object.</i> |
|-----------------|--------------------------------------|

Description

An example ENMevaluation object produced after running ENMevaluate() with feature classes L, LQ, LQH, H and regularization multipliers 1 through 5.

Usage

```
enmeval_results
```

Format

An ENMevaluation object

| | |
|---------------|----------------------|
| ENMnull-class | <i>ENMnull class</i> |
|---------------|----------------------|

Description

An S4 class that contains the ENMnulls results.

Usage

```
## S4 method for signature 'ENMnull'
show(object)
```

Arguments

object ENMnull object

Slots

```
null.algorithm character: algorithm used
null.mod.settings data frame: model settings used
null.partition.method character: partition method used
null.partition.settings list: partition settings used (i.e., value of *k* or aggregation factor)
null.other.settings list: other modeling settings used (i.e., decisions about clamping, AUC
diff calculation)
null.no.iter numeric: number of null model iterations
null.results data frame: evaluation summary statistics for null models
null.results.partitions data frame: evaluation k-fold statistics for null models
```

`null.emp.results` data frame: evaluation summary statistics for the empirical model, means for all null models, z-scores, and p-values

`emp.occs` data frame: occurrence coordinates and predictor variable values used for model training (empirical model)

`emp.occs.grp` vector: partition groups for occurrence points (empirical model)

`emp.bg` data frame: background coordinates and predictor variable values used for model training (empirical model)

`emp.bg.grp` vector: partition groups for background points (empirical model)

Author(s)

Jamie M. Kass, <jamie.m.kass@gmail.com>, Corentin Bohl, <corentinbohl@gmail.com>

ENMnulls

Generate null ecological niche models (ENMs) and compare null with empirical performance metrics

Description

`ENMnulls()` iteratively builds null ENMs for a single set of user-specified model settings based on an input `ENMevaluation` object, from which all other analysis settings are extracted. Summary statistics of the performance metrics for the null ENMs are taken (averages and standard deviations) and effect sizes and *p*-values are calculated by comparing these summary statistics to the empirical values of the performance metrics (i.e., from the model built with the empirical data). See the references below for more details on this method.

Usage

```
ENMnulls(
  e,
  mod.settings,
  no.iter,
  eval.stats = c("auc.val", "auc.diff", "cbi.val", "or.mtp", "or.10p"),
  user.enm = NULL,
  user.eval.type = NULL,
  userStats.signs = NULL,
  removeMxTemp = TRUE,
  parallel = FALSE,
  numCores = NULL,
  parallelType = "doSNOW",
  quiet = FALSE
)
```

Arguments

| | |
|------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <code>e</code> | ENMEvaluation object |
| <code>mod.settings</code> | named list: one set of model settings with which to build null ENMs |
| <code>no.iter</code> | numeric: number of null model iterations |
| <code>eval.stats</code> | character vector: the performance metrics that will be used to calculate null model statistics |
| <code>user.enm</code> | ENMdetails object: if implementing a user-specified model |
| <code>user.eval.type</code> | character: if implementing a user-specified model, specify here which evaluation type to use – either "knonspatial", "kspatial", "testing", or "none" |
| <code>userStats.signs</code> | named list: user-defined evaluation statistics attributed with either 1 or -1 to designate whether the expected difference between empirical and null models is positive or negative; this is used to calculate the p-value of the z-score |
| <code>removeMxTemp</code> | boolean: if TRUE, delete all temporary data generated when using maxent.jar for modeling |
| <code>parallel</code> | boolean: if TRUE, use parallel processing |
| <code>numCores</code> | numeric: number of cores to use for parallel processing; if NULL, all available cores will be used |
| <code>parallelType</code> | character:: either "doParallel" or "doSNOW" (default: "doSNOW") |
| <code>quiet</code> | boolean: if TRUE, silence all function messages (but not errors) |

Details

This null ENM technique is based on the implementation in Bohl *et al.* (2019), which follows the original methodology of Raes & ter Steege (2007) but makes an important modification: instead of evaluating each null model on random validation data, here we evaluate the null models on the same withheld validation data used to evaluate the empirical model. Bohl *et al.* (2019) demonstrates this approach using a single defined withheld partition group, but Kass *et al.* (2020) extended it to use spatial partitions by drawing null occurrences from the area of the predictor raster data defining each partition. Please see the vignette for a brief example: <

This function avoids using raster data to speed up each iteration, and instead samples null occurrences from the partitioned background records. Thus, you should avoid running this when your background records are not well sampled across the study extent, as this limits the extent that null occurrences can be sampled from.

Value

An ENMnull object with slots containing evaluation summary statistics for the null models and their cross-validation results, as well as differences in results between the empirical and null models. This comparison table includes z-scores of these differences and their associated p-values (under a normal distribution). See ?ENMnull for more details.

References

Bohl, C. L., Kass, J. M., & Anderson, R. P. (2019). A new null model approach to quantify performance and significance for ecological niche models of species distributions. *Journal of Biogeography*, **46**: 1101-1111. doi: [10.1111/jbi.13573](https://doi.org/10.1111/jbi.13573)

Kass, J. M., Anderson, R. P., Espinosa-Lucas, A., Juárez-Jaimes, V., Martínez-Salas, E., Botello, F., Tavera, G., Flores-Martínez, J. J., & Sánchez-Cordero, V. (2020). Biotic predictors with phenological information improve range estimates for migrating monarch butterflies in Mexico. *Ecography*, **43**: 341-352. doi: [10.1111/ecog.04886](https://doi.org/10.1111/ecog.04886)

Raes, N., & ter Steege, H. (2007). A null-model for significance testing of presence-only species distribution models. *Ecography*, **30**: 727-736. doi: [10.1111/j.2007.09067590.05041.x](https://doi.org/10.1111/j.2007.09067590.05041.x)

| | |
|----------------|--------------------------------------------------------|
| eval.algorithm | <i>eval.algorithm generic for ENMEvaluation object</i> |
|----------------|--------------------------------------------------------|

Description

eval.algorithm generic for ENMEvaluation object

Usage

```
eval.algorithm(x)

## S4 method for signature 'ENMEvaluation'
eval.algorithm(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMEvaluation object |
|---|----------------------|

| | |
|---------|-------------------------------------------------|
| eval.bg | <i>eval.bg generic for ENMEvaluation object</i> |
|---------|-------------------------------------------------|

Description

eval.bg generic for ENMEvaluation object

Usage

```
eval.bg(x)

## S4 method for signature 'ENMEvaluation'
eval.bg(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMEvaluation object |
|---|----------------------|

| | |
|-------------|-----------------------------------------------------|
| eval.bg.grp | <i>eval.bg.grp generic for ENMevaluation object</i> |
|-------------|-----------------------------------------------------|

Description

eval.bg.grp generic for ENMevaluation object

Usage

```
eval.bg.grp(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.bg.grp(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

| | |
|-----------------------|---------------------------------------------------------------|
| eval.clamp.directions | <i>eval.clamp.directions generic for ENMevaluation object</i> |
|-----------------------|---------------------------------------------------------------|

Description

eval.clamp.directions generic for ENMevaluation object

Usage

```
eval.clamp.directions(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.clamp.directions(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

eval.doClamp *eval.doClamp generic for ENMevaluation object*

Description

eval.doClamp generic for ENMevaluation object

Usage

```
eval.doClamp(x)

## S4 method for signature 'ENMevaluation'
eval.doClamp(x)
```

Arguments

x ENMevaluation object

eval.models *eval.models generic for ENMevaluation object*

Description

eval.models generic for ENMevaluation object

Usage

```
eval.models(x)

## S4 method for signature 'ENMevaluation'
eval.models(x)

## S4 method for signature 'ENMevaluation'
eval.models(x)
```

Arguments

x ENMevaluation object

| | |
|-----------|---------------------------------------------------|
| eval.occs | <i>eval.occs generic for ENMevaluation object</i> |
|-----------|---------------------------------------------------|

Description

eval.occs generic for ENMevaluation object

Usage

```
eval.occs(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.occs(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

| | |
|---------------|-------------------------------------------------------|
| eval.occs.grp | <i>eval.occs.grp generic for ENMevaluation object</i> |
|---------------|-------------------------------------------------------|

Description

eval.occs.grp generic for ENMevaluation object

Usage

```
eval.occs.grp(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.occs.grp(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

eval.occs.testing *eval.occs.testing generic for ENMevaluation object*

Description

eval.occs.testing generic for ENMevaluation object

Usage

```
eval.occs.testing(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.occs.testing(x)
```

Arguments

x ENMevaluation object

eval.other.settings *eval.other.settings generic for ENMevaluation object*

Description

eval.other.settings generic for ENMevaluation object

Usage

```
eval.other.settings(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.other.settings(x)
```

Arguments

x ENMevaluation object

| | |
|--------------|------------------------------------------------------|
| eval.overlap | <i>eval.overlap generic for ENMevaluation object</i> |
|--------------|------------------------------------------------------|

Description

eval.overlap generic for ENMevaluation object

Usage

```
eval.overlap(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.overlap(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

| | |
|-----------------------|---------------------------------------------------------------|
| eval.partition.method | <i>eval.partition.method generic for ENMevaluation object</i> |
|-----------------------|---------------------------------------------------------------|

Description

eval.partition.method generic for ENMevaluation object

Usage

```
eval.partition.method(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.partition.method(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

eval.partition.settings

eval.partition.settings generic for ENMevaluation object

Description

eval.partition.settings generic for ENMevaluation object

Usage

```
eval.partition.settings(x)
```

```
## S4 method for signature 'ENMevaluation'
```

```
eval.partition.settings(x)
```

Arguments

x ENMevaluation object

eval.predictions

eval.predictions generic for ENMevaluation object

Description

eval.predictions generic for ENMevaluation object

Usage

```
eval.predictions(x)
```

```
## S4 method for signature 'ENMevaluation'
```

```
eval.predictions(x)
```

Arguments

x ENMevaluation object

| | |
|--------------|------------------------------------------------------|
| eval.results | <i>eval.results generic for ENMevaluation object</i> |
|--------------|------------------------------------------------------|

Description

eval.results generic for ENMevaluation object

Usage

```
eval.results(x)  
  
## S4 method for signature 'ENMevaluation'  
eval.results(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

| | |
|-------------------------|-----------------------------------------------------------------|
| eval.results.partitions | <i>eval.results.partitions generic for ENMevaluation object</i> |
|-------------------------|-----------------------------------------------------------------|

Description

eval.results.partitions generic for ENMevaluation object

Usage

```
eval.results.partitions(x)  
  
## S4 method for signature 'ENMevaluation'  
eval.results.partitions(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

| | |
|----------|--------------------------------------------------|
| eval.rmm | <i>eval.rmm generic for ENMevaluation object</i> |
|----------|--------------------------------------------------|

Description

eval.rmm generic for ENMevaluation object

Usage

```
eval.rmm(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.rmm(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

| | |
|-----------------|---------------------------------------------------------|
| eval.taxon.name | <i>eval.taxon.name generic for ENMevaluation object</i> |
|-----------------|---------------------------------------------------------|

Description

eval.taxon.name generic for ENMevaluation object

Usage

```
eval.taxon.name(x)
```

```
## S4 method for signature 'ENMevaluation'  
eval.taxon.name(x)
```

Arguments

| | |
|---|----------------------|
| x | ENMevaluation object |
|---|----------------------|

eval.tune.settings *eval.tune.settings generic for ENMEvaluation object*

Description

eval.tune.settings generic for ENMEvaluation object

Usage

```
eval.tune.settings(x)
```

```
## S4 method for signature 'ENMEvaluation'  
eval.tune.settings(x)
```

Arguments

x ENMEvaluation object

eval.variable.importance
eval.variable.importance generic for ENMEvaluation object

Description

eval.variable.importance generic for ENMEvaluation object

Usage

```
eval.variable.importance(x)
```

Arguments

x ENMEvaluation object

evalplot.envSim.hist *Similarity histogram plots for partition groups*

Description

Plots environmental similarity of reference partitions (occurrences or background) to remaining background (all other partitions). This function does not use raster data, and thus only calculates similarity values for data used in model training. Further, this function does not calculate similarity for categorical variables.

Usage

```
evalplot.envSim.hist(
  e = NULL,
  occs.z = NULL,
  bg.z = NULL,
  occs.grp = NULL,
  bg.grp = NULL,
  ref.data = "occs",
  sim.type = "mess",
  categoricals = NULL,
  envs.vars = NULL,
  occs.testing.z = NULL,
  hist.bins = 30,
  return.tbl = FALSE,
  quiet = FALSE
)
```

Arguments

| | |
|----------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| e | ENMEvaluation object |
| occs.z | data frame: longitude, latitude, and environmental predictor variable values for occurrence records, in that order (optional); the first two columns must be named "longitude" and "latitude" |
| bg.z | data frame: longitude, latitude, and environmental predictor variable values for background records, in that order (optional); the first two columns must be named "longitude" and "latitude" |
| occs.grp | numeric vector: partition groups for occurrence records (optional) |
| bg.grp | numeric vector: partition groups for background records (optional) |
| ref.data | character: the reference to calculate MESS based on occurrences ("occs") or background ("bg"), with default "occs" |
| sim.type | character: either "mess" for Multivariate Environmental Similarity Surface, "most_diff" for most different variable, or "most_sim" for most similar variable; uses similarity function from package rmaxent |

| | |
|----------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| categoricals | character vector: names of categorical variables in input RasterStack or data frames to be removed from the analysis; these must be specified as this function was intended for use with continuous data only |
| envs.vars | character vector: names of a predictor variable to plot similarities for; if left NULL, calculations are done with respect to all variables (optional) |
| occs.testing.z | data frame: longitude, latitude, and environmental predictor variable values for fully withheld testing records, in that order; this is for use only with the "testing" partition option when an ENMEvaluation object is not input (optional) |
| hist.bins | numeric: number of histogram bins for histogram plots; default is 30 |
| return.tbl | boolean: if TRUE, return the data frames of similarity values used to make the ggplot instead of the plot itself |
| quiet | boolean: if TRUE, silence all function messages (but not errors) |

Details

When fully withheld testing groups are used, make sure to input either an ENMEvaluation object or the argument occs.testing.z. In the resulting plot, partition 1 refers to the training data, while partition 2 refers to the fully withheld testing group.

There are two variations for this plot. If "histogram", histograms are plotted showing the MESS estimates for each partition group. If "raster", rasters are plotted showing the geographical MESS estimates for each partition group. With sim.type option "mess", the similarity between environmental values associated with the validation occurrences (per partition group) and those associated with the entire study extent (specified by the extent of the input RasterStack "envs") are calculated, and the minimum similarity per grid is returned. Higher negative values indicate greater environmental difference between the validation occurrences and the study extent, and higher positive values indicate greater similarity. This function uses the 'similarity()' function to calculate the similarities. See the below reference for details on MESS.

Value

A ggplot of MESS calculations for data partitions.

References

Elith, J., Kearney, M., and Phillips, S. (2010) The art of modelling range-shifting species. *Methods in Ecology and Evolution*, **1**: 330-342. doi: [10.1111/j.2041210X.2010.00036.x](https://doi.org/10.1111/j.2041210X.2010.00036.x)

evalplot.envSim.map *Similarity maps for partition groups*

Description

Maps environmental similarity of reference partitions (occurrences or background) to all cells with values in the raster. This function uses raster data, and thus cannot map similarity values using only tables of environmental values for occurrences or background. Further, this function does not calculate similarity for categorical variables.

Usage

```
evalplot.envSim.map(
  e = NULL,
  envs,
  occs.z = NULL,
  bg.z = NULL,
  occs.grp = NULL,
  bg.grp = NULL,
  ref.data = "occs",
  sim.type = "mess",
  categoricals = NULL,
  envs.vars = NULL,
  bb.buf = 0,
  occs.testing.z = NULL,
  plot.bg.pts = FALSE,
  sim.palette = NULL,
  pts.size = 1.5,
  gradient.colors = c("red", "white", "blue"),
  na.color = "gray",
  return.tbl = FALSE,
  return.ras = FALSE,
  quiet = FALSE
)
```

Arguments

| | |
|--------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| e | ENMEvaluation object (optional) |
| envs | RasterStack: environmental predictor variables used to build the models in "e"; categorical variables should be removed before input, as they cannot be used to calculate MESS |
| occs.z | data frame: longitude, latitude, and environmental predictor variable values for occurrence records, in that order (optional); the first two columns must be named "longitude" and "latitude" |
| bg.z | data frame: longitude, latitude, and environmental predictor variable values for background records, in that order (optional); the first two columns must be named "longitude" and "latitude" |
| occs.grp | numeric vector: partition groups for occurrence records (optional) |
| bg.grp | numeric vector: partition groups for background records (optional) |
| ref.data | character: the reference to calculate MESS based on occurrences ("occs") or background ("bg"), with default "occs" |
| sim.type | character: either "mess" for Multivariate Environmental Similarity Surface, "most_diff" for most different variable, or "most_sim" for most similar variable; uses similarity function from package rmaxent |
| categoricals | character vector: names of categorical variables in input RasterStack or data frames to be removed from the analysis; these must be specified as this function was intended for use with continuous data only |

| | |
|-----------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| envs.vars | character vector: names of a predictor variable to plot similarities for; if left NULL, calculations are done with respect to all variables (optional) |
| bb.buf | numeric: distance used to buffer (extend) the mapping extent in map units; for latitude/longitude, this is in degrees (optional) |
| occs.testing.z | data frame: longitude, latitude, and environmental predictor variable values for fully withheld testing records, in that order; this is for use only with the "testing" partition option when an ENMevaluation object is not input (optional) |
| plot.bg.pts | boolean: if TRUE, plot background points when using ref.data = "bg" |
| sim.palette | character: RColorBrewer palette name to use for plotting discrete variables; if NULL, default is "Set1" |
| pts.size | numeric: custom point size for ggplot |
| gradient.colors | character vector: colors used for ggplot2::scale_fill_gradient2 |
| na.color | character: color used for NA values |
| return.tbl | boolean: if TRUE, return the data frames of similarity values used to make the ggplot instead of the plot itself |
| return.ras | boolean: if TRUE, return the RasterStack of similarity values used to make the ggplot instead of the plot itself |
| quiet | boolean: if TRUE, silence all function messages (but not errors) |

Details

When fully withheld testing groups are used, make sure to input either an ENMevaluation object or the argument occs.testing.z. In the resulting plot, partition 1 refers to the training data, while partition 2 refers to the fully withheld testing group.

There are two variations for this plot. If "histogram", histograms are plotted showing the MESS estimates for each partition group. If "raster", rasters are plotted showing the geographical MESS estimates for each partition group. With sim.type option "mess", the similarity between environmental values associated with the validation occurrences (per partition group) and those associated with the entire study extent (specified by the extent of the input RasterStack "envs") are calculated, and the minimum similarity per grid is returned. Higher negative values indicate greater environmental difference between the validation occurrences and the study extent, and higher positive values indicate greater similarity. This function uses the 'similarity()' function to calculate the similarities. See the below reference for details on MESS.

Value

A ggplot of MESS calculations for data partitions.

References

Elith, J., Kearney, M., and Phillips, S. (2010) The art of modelling range-shifting species. *Methods in Ecology and Evolution*, **1**: 330-342. doi: [10.1111/j.2041210X.2010.00036.x](https://doi.org/10.1111/j.2041210X.2010.00036.x)

evalplot.grps *Partition group plots*

Description

Plot occurrence partition groups over an environmental predictor raster.

Usage

```
evalplot.grps(  
  e = NULL,  
  envs,  
  pts = NULL,  
  pts.grp = NULL,  
  ref.data = "occs",  
  pts.size = 1.5,  
  return.tbl = FALSE  
)
```

Arguments

| | |
|------------|---------------------------------------------------------------------------------------------|
| e | ENMEvaluation object |
| envs | RasterStack: environmental predictor variable used to build the models in "e" |
| pts | matrix / data frame: coordinates for occurrence or background data |
| pts.grp | numeric vector: partition groups corresponding to data in "pts" |
| ref.data | character: plot occurrences ("occs") or background ("bg"), with default "occs" |
| pts.size | numeric: custom point size for ggplot |
| return.tbl | boolean: if TRUE, return the data frames used to make the ggplot instead of the plot itself |

Details

This function serves as a quick way to visualize occurrence or background partitions over the extent of an environmental predictor raster. It can be run with an existing ENMEvaluation object, or alternatively with occurrence or background coordinates and the corresponding partitions.

| | |
|----------------|---------------------------------|
| evalplot.nulls | <i>ENMnulls statistics plot</i> |
|----------------|---------------------------------|

Description

Plot histogram of evaluation statistics for null ENM simulations

Usage

```
evalplot.nulls(  
  e.null,  
  stats,  
  plot.type,  
  facet.labels = NULL,  
  metric.levels = NULL,  
  return.tbl = FALSE  
)
```

Arguments

| | |
|---------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| e.null | ENMnull object |
| stats | character vector: metrics from results table to be plotted; examples are "auc.val" or "or.10p"; if more than one statistic is specified, the histogram plot will be faceted |
| plot.type | character: either "violin" or "histogram" |
| facet.labels | named list: custom names for the metric facets, in the form list(old_name = "new_name", ...) |
| metric.levels | character vector: custom factor levels for metrics; this controls the order that metric statistics are plotted |
| return.tbl | boolean: if TRUE, return the data frames of null results used to make the ggplot instead of the plot itself |

Details

There are two variations for this plot, but both show null quantiles (0.01, 0.05, 0.5, 0.95, 0.99). For violin plots, the null distribution is displayed as a vertical shape (i.e., the violin) with horizontal lines showing the quantiles and the empirical value is plotted as a red point along the vertical axis. For histogram plots, the null distribution is displayed as a histogram with vertical lines showing the quantiles and the empirical value as a vertical red line on the distribution.

Value

A ggplot of null model statistics.

evalplot.stats

ENMEvaluation statistics plot

Description

Plot evaluation statistics over tuning parameter ranges to visualize differences in performance

Usage

```
evalplot.stats(
  e,
  stats,
  x.var,
  color.var,
  dodge = NULL,
  error.bars = TRUE,
  facet.labels = NULL,
  metric.levels = NULL,
  return.tbl = FALSE
)
```

Arguments

| | |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------|
| <code>e</code> | ENMEvaluation object |
| <code>stats</code> | character vector: names of statistics from results table to be plotted; if more than one statistic is specified, the plot will be faceted |
| <code>x.var</code> | character: variable to be plotted on x-axis |
| <code>color.var</code> | character: variable used to assign symbology colors |
| <code>dodge</code> | numeric: dodge width for points and lines; this improves visibility when there is high overlap (optional) |
| <code>error.bars</code> | boolean: if TRUE, plot error bars |
| <code>facet.labels</code> | character vector: custom names for the metric facets |
| <code>metric.levels</code> | character vector: custom factor levels for metrics; this controls the order that metric statistics are plotted |
| <code>return.tbl</code> | boolean: if TRUE, return the data frames of results used to make the ggplot instead of the plot itself |

Details

In this plot, the x-axis represents a tuning parameter range, while the y-axis represents the average of a statistic over all partitions. Different colors represent the categories or values of another tuning parameter. Error bars represent the standard deviation of a statistic around the mean. Currently, this function can only plot two tuning parameters at a time.

Value

A ggplot of evaluation statistics.

| | |
|------------|----------------------------------|
| lookup.enm | <i>Look up ENMdetails object</i> |
|------------|----------------------------------|

Description

Internal function to look up ENMdetails objects.

Usage

```
lookup.enm(algorithm)
```

Arguments

algorithm character: algorithm name (must be implemented as ENMdetails object)

| | |
|------------------|--------------------------------------|
| maxentJARversion | <i>Look up version of maxent.jar</i> |
|------------------|--------------------------------------|

Description

Internal function to look up the version of the maxent.jar being used.

Usage

```
maxentJARversion()
```

| | |
|----------------|--------------------------------------------------|
| null.algorithm | <i>null.algorithm generic for ENMnull object</i> |
|----------------|--------------------------------------------------|

Description

null.algorithm generic for ENMnull object

Usage

```
null.algorithm(x)
```

```
## S4 method for signature 'ENMnull'
null.algorithm(x)
```

Arguments

x ENMnull object

| | |
|------------------|----------------------------------------------------|
| null.emp.results | <i>null.emp.results generic for ENMnull object</i> |
|------------------|----------------------------------------------------|

Description

null.emp.results generic for ENMnull object

Usage

```
null.emp.results(x)
```

```
## S4 method for signature 'ENMnull'  
null.emp.results(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

| | |
|-------------------|-----------------------------------------------------|
| null.mod.settings | <i>null.mod.settings generic for ENMnull object</i> |
|-------------------|-----------------------------------------------------|

Description

null.mod.settings generic for ENMnull object

Usage

```
null.mod.settings(x)
```

```
## S4 method for signature 'ENMnull'  
null.mod.settings(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

| | |
|--------------|------------------------------------------------|
| null.no.iter | <i>null.no.iter generic for ENMnull object</i> |
|--------------|------------------------------------------------|

Description

null.no.iter generic for ENMnull object

Usage

```
null.no.iter(x)
```

```
## S4 method for signature 'ENMnull'  
null.no.iter(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

| | |
|---------------------|-------------------------------------------------------|
| null.other.settings | <i>null.other.settings generic for ENMnull object</i> |
|---------------------|-------------------------------------------------------|

Description

null.other.settings generic for ENMnull object

Usage

```
null.other.settings(x)
```

```
## S4 method for signature 'ENMnull'  
null.other.settings(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

null.partition.method *null.partition.method generic for ENMnull object*

Description

null.partition.method generic for ENMnull object

Usage

```
null.partition.method(x)  
  
## S4 method for signature 'ENMnull'  
null.partition.method(x)
```

Arguments

x ENMnull object

null.partition.settings
null.partition.settings generic for ENMnull object

Description

null.partition.settings generic for ENMnull object

Usage

```
null.partition.settings(x)  
  
## S4 method for signature 'ENMnull'  
null.partition.settings(x)
```

Arguments

x ENMnull object

| | |
|--------------|------------------------------------------------|
| null.results | <i>null.results generic for ENMnull object</i> |
|--------------|------------------------------------------------|

Description

null.results generic for ENMnull object

Usage

```
null.results(x)

## S4 method for signature 'ENMnull'
null.results(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

| | |
|-------------------------|-----------------------------------------------------------|
| null.results.partitions | <i>null.results.partitions generic for ENMnull object</i> |
|-------------------------|-----------------------------------------------------------|

Description

null.results.partitions generic for ENMnull object

Usage

```
null.results.partitions(x)

## S4 method for signature 'ENMnull'
null.results.partitions(x)
```

Arguments

| | |
|---|----------------|
| x | ENMnull object |
|---|----------------|

Description

ENMeval provides several ways to partition occurrence and background localities into bins for training and validation (or, evaluation and calibration). Users should carefully consider the objectives of their study and the influence of spatial bias when deciding on a method of data partitioning.

These functions are used internally to partition data during a call of **ENMevaluate** but can also be used independently to generate data partitions. For user-specified partitions, users can simply define groups of occurrence records and background points directly with **ENMevaluate**.

The `get.block` method partitions occurrence localities by finding the latitude and/or longitude lines that divide the occurrence localities into four groups of (insofar as possible) equal numbers. The order and nature of the divisions can be controlled with the "orientation" parameter. The default is "lat_lon", which divides first by a latitudinal line, then second by longitudinal lines. This method is based on the spatial partitioning technique described in Radosavljevic & Anderson (2014), where the "lon_lon" option was used. Background localities are assigned to each of the four groups based on their position with respect to these lines. While the `get.block` method results in (approximately) equal division of occurrence localities among four groups, the number of background localities (and, consequently, environmental and geographic space) in each group depends on the distribution of occurrence localities across the study area.

The `get.checkerboard1` and `get.checkerboard2` methods are variants of a checkerboard approach to partition occurrence localities. These methods use the `dismo::gridSample` function of the **dismo** package (Hijmans *et al.* 2011) to partition records according to checkerboard grids across the study extent. The spatial grain of these grids is determined by resampling (or aggregating) the original environmental input grids based on the user-defined aggregation factor (e.g., an aggregation factor of 2 results in a checkerboard with grid cells four times as large in area as the original input grids). The `get.checkerboard1` method partitions data into two groups according to a single checkerboard pattern, and the `get.checkerboard2` method partitions data into four groups according to two nested checkerboard grids. In contrast to the `get.block` method, both the `get.checkerboard1` and `get.checkerboard2` methods subdivide geographic space equally but do not ensure a balanced number of occurrence localities in each group. The two `get.checkerboard` methods give warnings (and potentially errors) if zero points (occurrence or background) fall in any of the expected bins.

The `get.jackknife` method is a special case of k -fold cross validation where the number of bins (k) is equal to the number of occurrence localities (n) in the dataset. It is suggested for occurrence datasets of relatively small sample size (generally < 25 localities) (Pearson *et al.* 2007; Shcheglovitova and Anderson 2013).

The `get.randomkfold` method partitions occurrence localities randomly into a user-specified number of (k) bins. This is equivalent to the method of k -fold cross validation currently provided by **Maxent**.

Users can also define custom partitions for occurrence and background data in the call to 'ENMevaluate' with the "user.grp" parameter.

Usage

```

get.block(occs, bg, orientation = "lat_lon")

get.checkerboard1(occs, envs, bg, aggregation.factor, gridSampleN = 10000)

get.checkerboard2(occs, envs, bg, aggregation.factor, gridSampleN = 10000)

get.jackknife(occs, bg)

get.randomkfold(occs, bg, kfolds)

```

Arguments

| | |
|--------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| occs | matrix / data frame: longitude and latitude (in that order) of occurrence localities |
| bg | matrix / data frame: longitude and latitude (in that order) of background localities |
| orientation | character vector: the order of spatial partitioning for the <code>get.block</code> method; the first direction bisects the points into two groups, and the second direction bisects each of these further into two groups each, resulting in four groups; options are "lat_lon" (default), "lon_lat", "lon_lon", and "lat_lat" |
| envs | RasterStack: environmental predictor variables |
| aggregation.factor | numeric vector: the aggregation scale for the <code>get.checkerboard1</code> and <code>get.checkerboard2</code> methods; if a single number is given and <code>get.checkerboard2</code> partitioning method is used, the single value is used for both scales of aggregation |
| gridSampleN | numeric: the number of points sampled from the input raster using <code>gridSample()</code> by the checkerboard partitioning functions |
| kfolds | numeric: number of random k -folds for <code>get.randomkfold</code> method |

Value

A named list of two items:

| | |
|-------------------------|---------------------------------------------------------------------------------------------|
| <code>\$occs.grp</code> | A vector of bin designation for occurrence localities in the same order they were provided. |
| <code>\$bg.grp</code> | A vector of bin designation for background localities in the same order they were provided. |

Note

The `checkerboard1` and `checkerboard2` methods are designed to partition occurrence localities into two and four evaluation bins, respectively. They may give fewer bins, however, depending on where the occurrence localities fall with respect to the grid cells (e.g., all records happen to fall in the "black" squares). A warning is given if the number of bins is < 4 for the `checkerboard2` method, and an error is given if all localities fall into a single evaluation bin.

Author(s)

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References

Hijmans, R. J., Phillips, S., Leathwick, J. and Elith, J. (2011). dismo package for R. Available online at: <https://cran.r-project.org/package=dismo>.

Pearson, R. G., Raxworthy, C. J., Nakamura, M. and Peterson, A. T. (2007). Predicting species distributions from small numbers of occurrence records: a test case using cryptic geckos in Madagascar. *Journal of Biogeography*, **34**: 102-117. doi: [10.1111/j.13652699.2006.01594.x](https://doi.org/10.1111/j.13652699.2006.01594.x)

Radosavljevic, A., & Anderson, R. P. (2014). Making better Maxent models of species distributions: complexity, overfitting and evaluation. *Journal of Biogeography*, **41**: 629-643. doi: [10.1111/jbi.12227](https://doi.org/10.1111/jbi.12227)

Shcheglovitova, M. and Anderson, R. P. (2013). Estimating optimal complexity for ecological niche models: a jackknife approach for species with small sample sizes. *Ecological Modelling*, **269**: 9-17. doi: [10.1016/j.ecolmodel.2013.08.011](https://doi.org/10.1016/j.ecolmodel.2013.08.011)

Examples

```
require(raster)

set.seed(1)

### Create environmental extent (raster)
envs <- raster(matrix(nrow=25, ncol=25))

### Create occurrence localities
set.seed(1)
nocc <- 25
xocc <- rnorm(nocc, sd=0.25) + 0.5
yocc <- runif(nocc, 0, 1)
occs <- as.data.frame(cbind(xocc, yocc))

### Create background points
nbg <- 500
xbg <- runif(nbg, 0, 1)
ybg <- runif(nbg, 0, 1)
bg <- as.data.frame(cbind(xbg, ybg))

### Plot points on environmental raster
plot(envs)
points(bg)
points(occs, pch=21, bg=2)

### Block partitioning method (default orientation is "lat_lon")
blk.latLon <- get.block(occs, bg)
plot(envs)
points(occs, pch=23, bg=blk.latLon$occs.grp)
plot(envs)
points(bg, pch=21, bg=blk.latLon$bg.grp)
```

```
# Can partition with other orientations
blk.latLat <- get.block(occs, bg, orientation = "lat_lat")
plot(envs)
points(occs, pch=23, bg=blk.latLat$occs.grp)
plot(envs)
points(bg, pch=21, bg=blk.latLat$bg.grp)

### Checkerboard1 partitioning method with aggregation factor of 4
chk1.ag4 <- get.checkerboard1(occs, envs, bg, aggregation.factor = 4)
plot(envs)
points(occs, pch=23, bg=chk1.ag4$occs.grp)
plot(envs)
points(bg, pch=21, bg=chk1.ag4$bg.grp)
# Higher aggregation factors result in bigger checkerboard blocks
chk1.ag8 <- get.checkerboard1(occs, envs, bg, aggregation.factor = 8)
plot(envs)
points(occs, pch=23, bg=chk1.ag8$occs.grp)
plot(envs)
points(bg, pch=21, bg=chk1.ag8$bg.grp)

### Checkerboard2 partitioning method with aggregation factors of 2, 2
chk2.ag2_2 <- get.checkerboard2(occs, envs, bg, c(2,2))
plot(envs)
points(occs, pch=23, bg=chk2.ag2_2$occs.grp)
plot(envs)
points(bg, pch=21, bg=chk2.ag2_2$bg.grp)
# Higher aggregation factors result in bigger checkerboard blocks,
# and can vary between hierarchical levels
chk2.ag4_6 <- get.checkerboard2(occs, envs, bg, c(4,6))
plot(envs)
points(occs, pch=23, bg=chk2.ag4_6$occs.grp)
plot(envs)
points(bg, pch=21, bg=chk2.ag4_6$bg.grp)

### Random partitions with 4 folds
# Note that get.randomkfold does not partition the background
krandom <- get.randomkfold(occs, bg, 4)
plot(envs)
points(occs, pch=23, bg=krandom$occs.grp)
plot(envs)
points(bg, pch=21, bg=krandom$bg.grp)

### k-1 jackknife partitions
# Note that get.jackknife does not partition the background
jack <- get.jackknife(occs, bg)
plot(envs)
points(occs, pch=23, bg=rainbow(length(jack$occs.grp)))
plot(envs)
points(bg, pch=21, bg=jack$bg.grp)
```

| | |
|-------------|---------------------------------------|
| rasStackNAs | <i>Find NA cells in a RasterStack</i> |
|-------------|---------------------------------------|

Description

Finds cells that are NA for at least one raster in a RasterStack.

Usage

```
rasStackNAs(envs)
```

Arguments

| | |
|------|-------------|
| envs | RasterStack |
|------|-------------|

| | |
|------------|--------------------------------------------------------|
| similarity | <i>Calculate Multivariate Environmental Similarity</i> |
|------------|--------------------------------------------------------|

Description

NOTICE: This function was borrowed from the rmaxent package written by John Baumgartner (<https://github.com/johnbaums/rmaxent/>).

Calculate Multivariate Environmental Similarity and most dissimilar/similar variables with respect to a reference dataset, for a set of environmental variables.

Usage

```
similarity(x, ref, full = FALSE)
```

Arguments

| | |
|------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| x | a 'Raster*', 'list', 'matrix', or 'data.frame' where each layer/column/element represents focal values of an environmental variable. |
| ref | a 'list', 'matrix', or 'data.frame' where each column/element represents reference values for an environmental variable (corresponding to those given in 'x'). |
| full | (logical) should similarity values be returned for all variables? If 'FALSE' (the default), then only the minimum similarity scores across variables will be returned. |

Details

'similarity' uses the MESS algorithm described in Appendix S3 of Elith *et al.* 2010.

Value

If 'x' is a 'Raster*' object, this function returns a list containing: - 'similarity': a 'RasterStack' giving the environmental similarities for each variable in 'x' (only included when 'full=TRUE'); - 'similarity_min': a 'Raster' layer giving the minimum similarity value across all variables for each location (i.e. the MESS); - 'mod': a factor 'Raster' layer indicating which variable was most dissimilar to its reference range (i.e. the MoD map, Elith *et al.* 2010); and - 'mos': a factor 'Raster' layer indicating which variable was most similar to its reference range.

If 'x' is a 'list', 'matrix', or 'data.frame', the function will return a list as above, but with 'RasterStack' and 'Raster' objects replaced by matrix and vectors.

References

Elith, J., Kearney, M., and Phillips, S. (2010) The art of modelling range-shifting species. *Methods in Ecology and Evolution*, 1: 330-342. doi: [10.1111/j.2041210X.2010.00036.x](https://doi.org/10.1111/j.2041210X.2010.00036.x)

Examples

```
library(dismo)
library(raster)
ff <- list.files(system.file('ex', package='dismo'), '\\.grd$',
                full.names=TRUE )
predictors <- stack(grep('biome', ff, value=TRUE, invert=TRUE))
occ <- read.csv(system.file('ex/bradypus.csv', package='dismo'))[, -1]
ref <- extract(predictors, occ)
mess <- similarity(predictors, ref, full=TRUE)

## Not run:
library(rasterVis)
library(RColorBrewer)
levelplot(mess$mod, col.regions=brewer.pal(8, 'Set1'))
levelplot(mess$mos, col.regions=brewer.pal(8, 'Set1'))

## End(Not run)
```

Description

Internal functions to tune and summarize results for ecological niche models (ENMs) iteratively across a range of user-specified tuning settings. See [ENMevaluate](#) for descriptions of shared arguments. Function `tune.parallel()` tunes ENMs with parallelization. Function `cv.enm()` calculates training and validation evaluation statistics for one set of specified tuning parameters.

Validation CBI is calculated here with background values, not raster data, in order to standardize the methodology for both training and validation data for spatial partitions, as ENMeval does not mask rasters to partition areas and hence does not have partitioned raster data. Further, predictions for occurrence and background localities are combined as input for the parameter "fit" in `boyce.cm()` because the interval is determined from "fit" only, and if test occurrences all have higher predictions than the background, the interval will be cut short.

Usage

```
tune.train(  
  enm,  
  occs.z,  
  bg.z,  
  mod.full,  
  envs,  
  tune.tbl.i,  
  other.settings,  
  partitions,  
  quiet  
)  
  
tune.validate(  
  enm,  
  occs.train.z,  
  occs.val.z,  
  bg.train.z,  
  bg.val.z,  
  mod.k,  
  nk,  
  tune.tbl.i,  
  other.settings,  
  partitions,  
  user.eval,  
  quiet  
)  
  
tune.parallel(  
  d,  
  envs,  
  enm,  
  partitions,  
  tune.tbl,  
  other.settings,  
  partition.settings,  
  user.val.grps,  
  occs.testing.z,  
  numCores,  
  parallelType,  
  user.eval,  
  quiet  
)  
  
tune.regular(  
  d,  
  envs,  
  enm,
```

```

    partitions,
    tune.tbl,
    other.settings,
    partition.settings,
    user.val.grps,
    occs.testing.z,
    updateProgress,
    user.eval,
    quiet
  )
)

cv.enm(
  d,
  envs,
  enm,
  partitions,
  tune.tbl.i,
  other.settings,
  partition.settings,
  user.val.grps,
  occs.testing.z,
  user.eval,
  quiet
)

```

Arguments

| | |
|----------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| enm | ENMdetails object |
| occs.z | data.frame: the envs values for the coordinates at the full dataset occurrence records |
| bg.z | data.frame: the envs values for the coordinates at the full dataset background records |
| mod.full | model object: the model trained on the full dataset |
| envs | RasterStack: environmental predictor variables. These should be in same geographic projection as occurrence data. |
| tune.tbl.i | vector: single set of tuning parameters |
| other.settings | named list: used to specify extra settings for the analysis. All of these settings have internal defaults, so if they are not specified the analysis will be run with default settings. See Details for descriptions of these settings. |
| partitions | character: name of partitioning technique (see ?partitions) |
| quiet | boolean: if TRUE, silence all function messages (but not errors). |
| occs.train.z | data.frame: the envs values for the coordinates at the training occurrence records |
| occs.val.z | data.frame: the envs values for the coordinates at the validation occurrence records |
| bg.train.z | data.frame: the envs values for the coordinates at the training background records |

| | |
|---------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <code>bg.val.z</code> | data.frame: the envs values for the coordinates at the validation background records |
| <code>mod.k</code> | model object: the model trained on the training dataset that becomes evaluated on the validation data |
| <code>nk</code> | numeric: the number of folds (i.e., partitions) – will be equal to <code>kfolds</code> for random partitions |
| <code>user.eval</code> | function: custom function for specifying performance metrics not included in ENMeval . The function must first be defined and then input as the argument <code>user.eval</code> . This function should have a single argument called <code>vars</code> , which is a list that includes different data that can be used to calculate the metric. See Details below and the vignette for a worked example. |
| <code>d</code> | data frame: data frame from <code>ENMevaluate()</code> with occurrence and background coordinates (or coordinates plus predictor variable values) and partition group values |
| <code>tune.tbl</code> | data frame: all combinations of tuning parameters |
| <code>partition.settings</code> | named list: used to specify certain settings for partitioning schema. See Details and <code>?partitions</code> for descriptions of these settings. |
| <code>user.val.grps</code> | matrix / data frame: user-defined validation record coordinates and predictor variable values. This is used internally by <code>ENMnulls()</code> to force each null model to evaluate with empirical validation data, and does not have any current use when running <code>ENMevaluate()</code> independently. |
| <code>occs.testing.z</code> | data.frame: when fully withheld testing data is provided, the envs values for the coordinates at the testing occurrence records |
| <code>numCores</code> | numeric: number of cores to use for parallel processing. If <code>NULL</code> , all available cores will be used. |
| <code>parallelType</code> | character: either "doParallel" or "doSNOW" (default: "doSNOW"). |
| <code>updateProgress</code> | boolean: if <code>TRUE</code> , use shiny progress bar. This is only for use in shiny apps. |

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